## **D3.2 IFS -ECMVF**

#### Manual and Automated Vectorisation for the Integrated Forecasting System

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## **EUPEX**



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## Introduction

> Summary of effects and strategies to utilise Arm ISAs

- Scalable Vector Extension (SVE)
- HBM (available on Fujitsu's A64FX processor)
- > CloudSC
  - Physics component of the Integrated Forecasting System (IFS)
    - A cloud microphysics parameterisation
  - Known for being computationally demanding

> Brief overview of co-design with ECMWF, Eviden, EUPEX, ESiWACE, and the EPI

# Effects of vectorisation on performance

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Performance of CloudSC without vectorisation, with auto-vectorisation, a handwritten SVE kernel, & auto-vectorised refactored kernel

- > Auto-vectorisation boosts performance by 87.6%
- Refactoring the hottest loop yields an increase of 57.9% over base performance
- Handwritten SVE intrinsics kernel written in C and called from Fortran achieves 95.6% of performance of the autovectorised refactored loop
- > Only **5.87% of maximum** theoretical **FLOPS per node**

**ECMWF** 

EUPEX



Performance of CloudSC without vectorisation, with auto-vectorisation, a handwritten SVE kernel, & auto-vectorised refactored kernel

## Using C SVE intrinsics in Fortran

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Fortran vs C Vectorisation Performance - Fortran Baseline

#### > The **IFS**, and by extension CloudSC, is written almost entirely in Fortran

- Not feasible to translate the whole codebase
- SVE intrinsics are only available in C

**ECMWF** 

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#### Fortran vs C Vectorisation Performance - Fortran Baseline

- The solution is to identify hot sections of the codebase and hand write SVE kernels for these in C, which can be called from Fortran
- Fortran is aligned to 64 bytes, while C is aligned to 16 by default
  - Only aligning to 64 bytes gave a performance increase over baseline
  - Aligning to 16 bytes gave a performance regression

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#### Fortran vs C Vectorisation Performance - Fortran Baseline

## Impact of memory bandwidth on CloudSC

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Roofline graph for the A64FX processor of CloudSC with various optimisations applied. Theoretical bounds used

#### CloudSC is known to be compute intensive and often not bound by memory bandwidth.

- > Performance is modelled with a naïve equation:  $T_1 = T_0 \alpha(f_0/f_1) + T_0 \beta(BW_0/BW_1)$
- Runs were taken varying only the CPU frequency, as it is the easiest of the two variables
- α = 0.651 & β = 0.343 for CloudSC
- Not memory bound at practical problem sizes



## Work for the future

- > Better overall performance
  - Currently CloudSC is only achieving ~6% of maximum theoretical FLOPS
  - How do we make it better?



#### Use Loki to automate the process of writing SVE kernels

- A source-to-source translation tool
- Recipes can be tailored to ECMWF code bases
- We can make more assumptions than the compiler can
- Directives can give more explicit hints to Loki
- Vectorise at the source code level, so no reliance on new compilers

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CloudSC on a Fujitsu A64FX node vs ECMWF's current operational AMD EPYC 7742 node

## **Loki in Action**

#### . . .

s = 0 do a=1, 3do b=1, a s = s + a + b + 1end do end do



Constant propagation

#### .

 $\mathbf{s} = \mathbf{0}$ s = 3s = 7s = 12s = 17s = 23s = 30

## **Discoveries Since D3.2**

> CloudSC wastes a lot of stack space on temporaries

- This can pollute the cache and greatly decrease performance
- > A lot of the branching can be eliminated with branchless programming techniques
  - CloudSC often branches within loops depending on the state of precipitation within clouds - rain, snow, hail, etc.
  - This enables more SIMD code generation

## **An Example of Branchless Programming**

#### ....

```
DO JM=1,NCLV-1
 DO JK=1,KLEV
    DO JL=KIDIA,KFDIA
      IF (ZQX(JL, JK, JM)<RLMIN) THEN
        ZLNEG(JL, JK, JM) = ZLNEG(JL, JK, JM) + ZQX(JL, JK, JM)
                         = ZQX(JL,JK,JM)*ZQTMST
        ZOADJ
        tendency_loc%q(JL,JK) = tendency_loc%q(JL,JK)+ZQADJ
        IF (IPHASE(JM)==1) THEN
            tendency_loc%T(JL,JK) = tendency_loc%T(JL,JK)-RALVDCP*ZQADJ
        ENDIF
        IF (IPHASE(JM)==2) THEN
            tendency_loc%T(JL,JK) = tendency_loc%T(JL,JK)-RALSDCP*ZQADJ
        ENDIF
        ZQX(JL, JK, NCLDQV)
                            = ZQX(JL, JK, NCLDQV) + ZQX(JL, JK, JM)
        ZOX(JL, JK, JM)
                             = 0.0 JPRB
      ENDIF
    ENDDO
  ENDDO
ENDDO
```

#### . . .

```
RALVVEC(1) = RALVDCP
RALVVEC(2) = RALSDCP
```

```
DO JM=1,NCLV-1
  DO JK=1,KLEV
    DO JL=KIDIA,KFDIA
      IF (ZQX(JL, JK, JM) < RLMIN) THEN
        ZLNEG(JL, JK, JM) = ZLNEG(JL, JK, JM) + ZQX(JL, JK, JM)
                         = ZQX(JL,JK,JM)*ZQTMST
        ZOADJ
        tendency_loc%q(JL,JK) = tendency_loc%q(JL,JK)+ZQADJ
        tendency_loc%T(JL,JK) = tendency_loc%T(JL,JK)-RALVVEC(JM)*ZQADJ
        ZQX(JL, JK, NCLDQV) = ZQX(JL, JK, NCLDQV) + ZQX(JL, JK, JM)
        ZQX(JL, JK, JM)
                             = 0.0 JPRB
      ENDIF
    ENDDO
  ENDDO
ENDDO
```



## **EUPEX and ESiWACE CoE**

#### > ESiWACE: Excellence in Simulation of Weather and Climate in EU

- High Performance Climate and Weather benchmark suite
  - Compares performance & performance portability on different HPC systems (CPU, GPU, Memory hierarchy, etc.)
  - Deployed on various x86 and aarch64 CPUs, explore software stack capability and obtained performance metrics, identify code optimization opportunities and give feedback to developers and technology providers
  - Leads to exchange of ideas with developers, technology providers and HPC vendors (i.e. co-design)
  - Include IFS dwarfs: ecRad, ecTrans, Dwarf-P-CloudSC
    - The reference test cases are currently defined by ECMWF in ESiWACE: Configuration, reference input data, output data validation, timing extraction
  - Periodic meeting between Eviden and ECMWF to synchronize and exchange technical information











#### EUPEX, ESIWACE COE, and EPI Co-Design in Action

#### > ecTrans, early results 🛛 💳

#### > CloudSC, HBM Assessment

Intel Xeon Max (Sapphire Rapids w. HBM)



ecTrans - Case1-SP - Execution Time (ms)



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